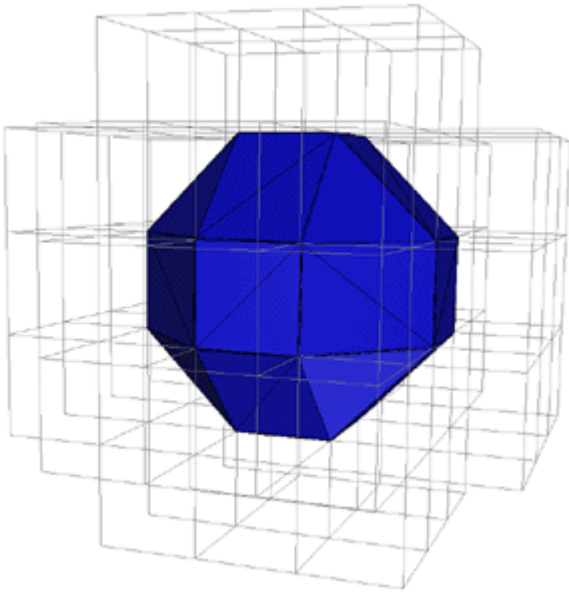


# Marching Cubes

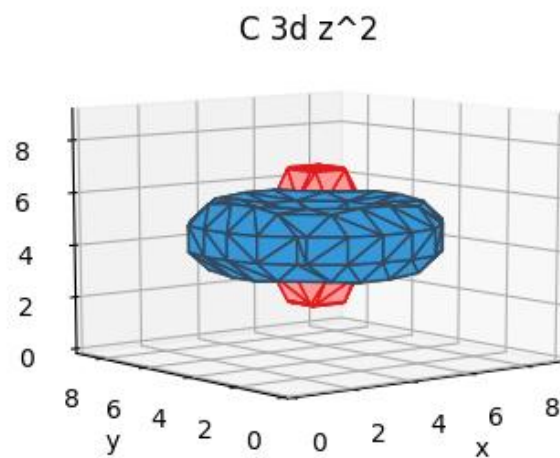
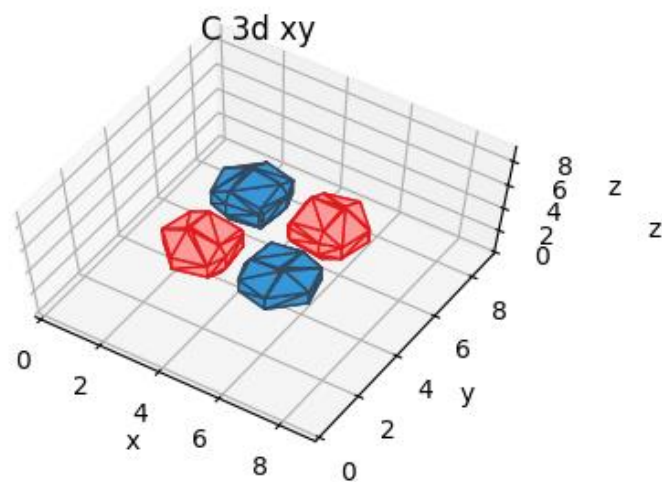
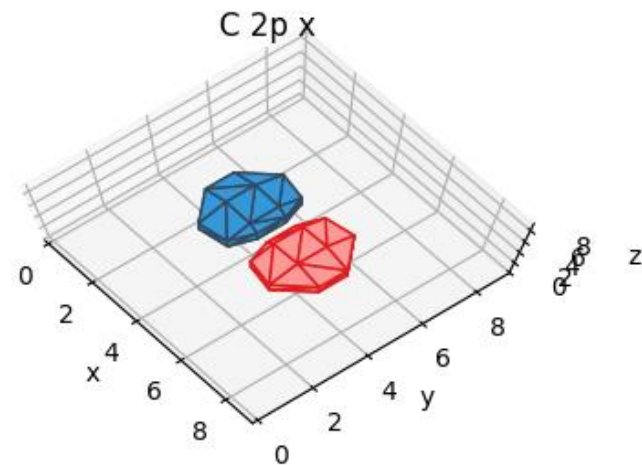
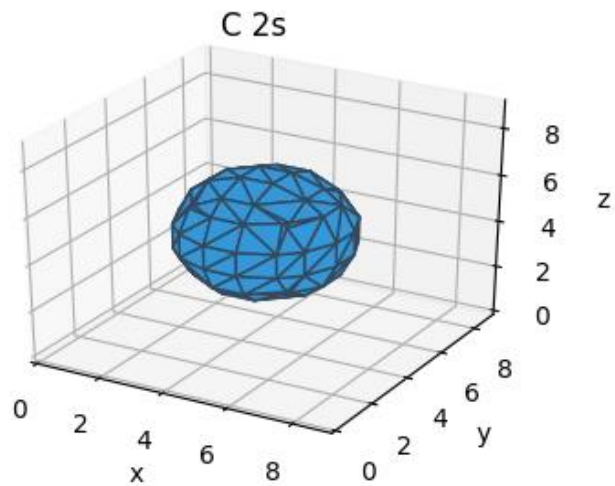
Yubo “Paul” Yang, Algorithm Group, 2017/09/12



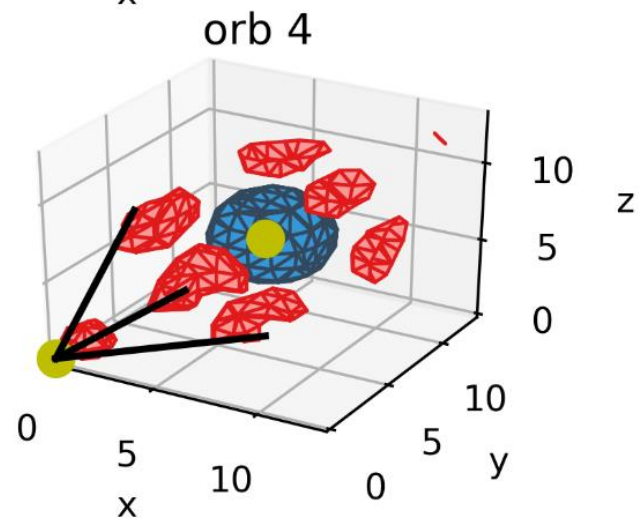
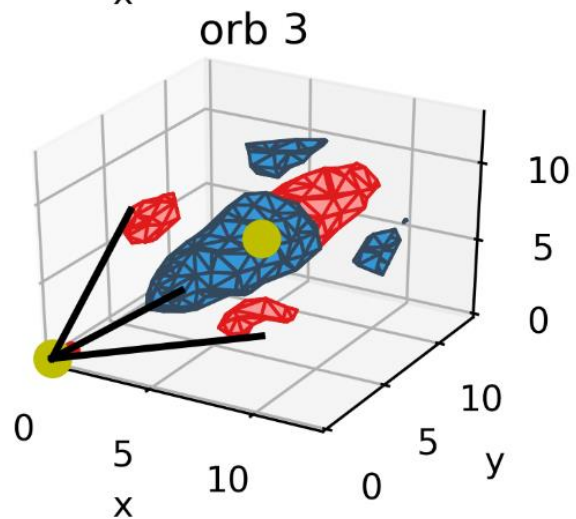
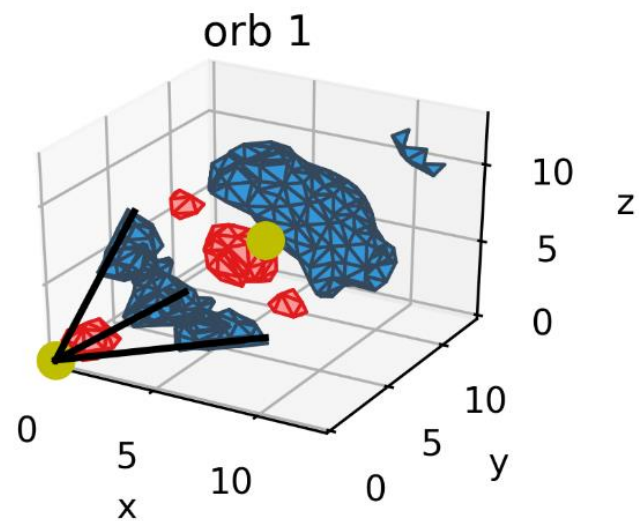
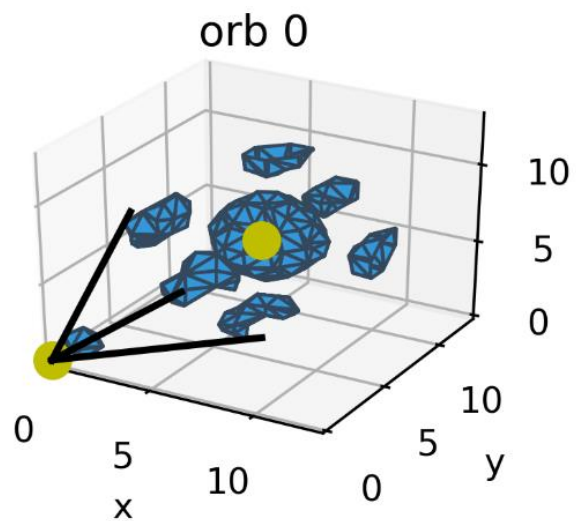
Ref: Paul Bourke, “Polygonising a scalar field,”  
<http://paulbourke.net/geometry/polygonise/>

Rawkstar, “Game Art, Necromancer General,”  
ZBrushCentral

# Showcase I: s,p,d basis function



## Showcase II: carbon diamond Hatree-Fock orbitals



## “The” Problem: Isosurface Extraction

Find N-1 representation of the zero-crossings of an N dimensional scalar field  $f(\vec{x}) = 0$ .

To simplify discussion:

1. restrict to 3 dimensions
2. assume scalar field is sampled on a regular grid

# “The” Problem: Polygonising a Scalar Field

Form a facet approximation for an isosurface of a scalar field sampled on a rectangular 3D grid.

**3x3x3 samples of  $e^{-r^2}$**

```
3D volumetric data:
[[[ 1.10363832  1.73575888  1.10363832]
  [ 1.73575888  2.36787944  1.73575888]
  [ 1.10363832  1.73575888  1.10363832]]
 [[ 1.73575888  2.36787944  1.73575888]
  [ 2.36787944  3.         2.36787944]
  [ 1.73575888  2.36787944  1.73575888]]
 [[ 1.10363832  1.73575888  1.10363832]
  [ 1.73575888  2.36787944  1.73575888]
  [ 1.10363832  1.73575888  1.10363832]]]
isovalue: 2.620728
```



```
vert[faces]
[[[ 1.         0.40000004  1.         ]
  [ 1.         1.         0.40000004]
  [ 0.40000004  1.         1.         ]]
 [[ 0.40000004  1.         1.         ]
  [ 1.         1.         1.59999999]
  [ 1.         0.40000004  1.         ]]
 [[ 1.         1.         0.40000004]
  [ 1.         1.59999999  1.         ]
  [ 0.40000004  1.         1.         ]]
 [[ 0.40000004  1.         1.         ]
  [ 1.         1.59999999  1.         ]
  [ 1.         1.         1.59999999 ]]
 [[ 1.59999999  1.         1.         ]
  [ 1.         1.         0.40000004]
  [ 1.         0.40000004  1.         ]]
 [[ 1.         1.         1.59999999]
  [ 1.59999999  1.         1.         ]
  [ 1.         0.40000004  1.         ]]
 [[ 1.59999999  1.         1.         ]
  [ 1.         1.59999999  1.         ]
  [ 1.         1.         0.40000004]]
 [[ 1.         1.59999999  1.         ]
  [ 1.59999999  1.         1.         ]
  [ 1.         1.         1.59999999 ]]]
```

**Triangle 1**

**Triangle 2**

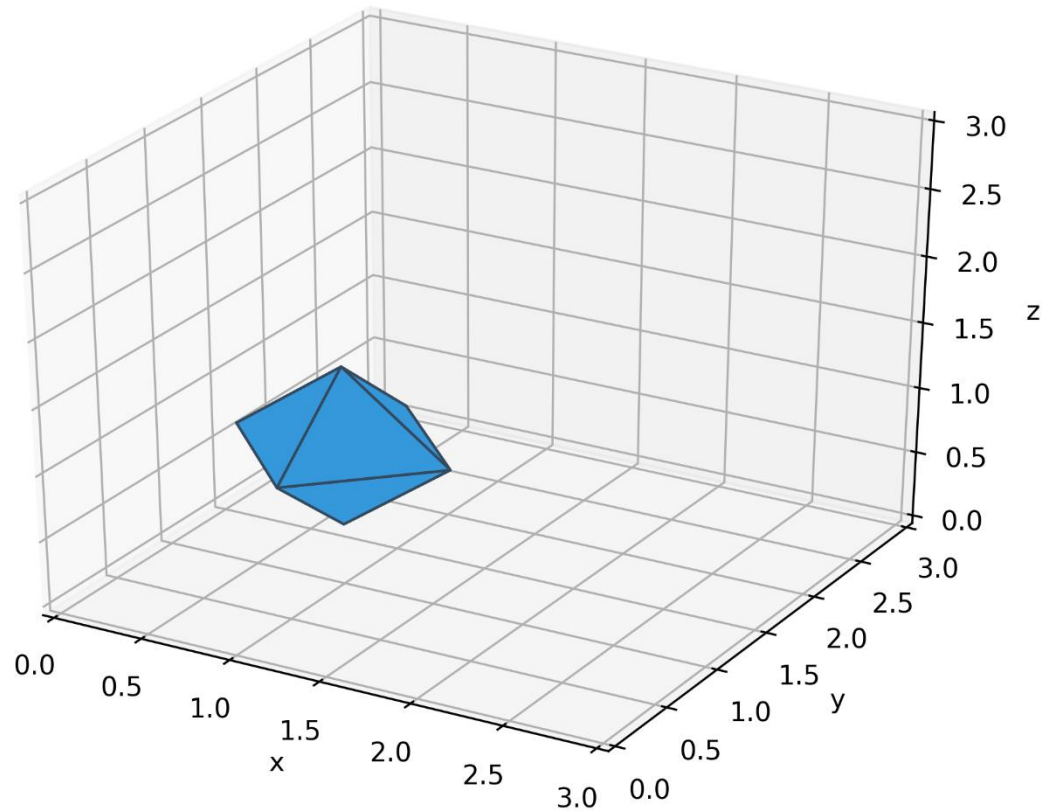
**Triangle 3**

**⋮**

**Triangle 8**

Solution: March through the voxels (cubes) and make polygons (cubes)

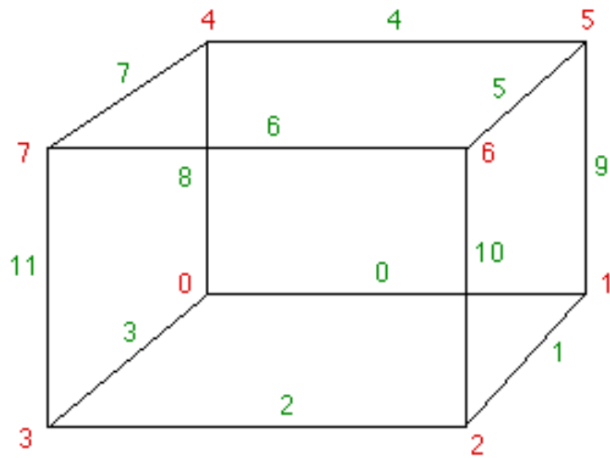
This is what a Gaussian looks like!



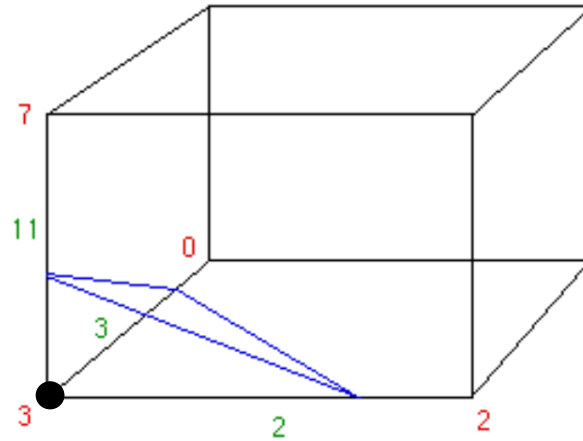
# “The” Implementation of Marching Cubes

by Paul Bourke

Ref: “Polygonising a scalar field”, <http://paulbourke.net/geometry/polygonise/>



Edge index  
Vertex index



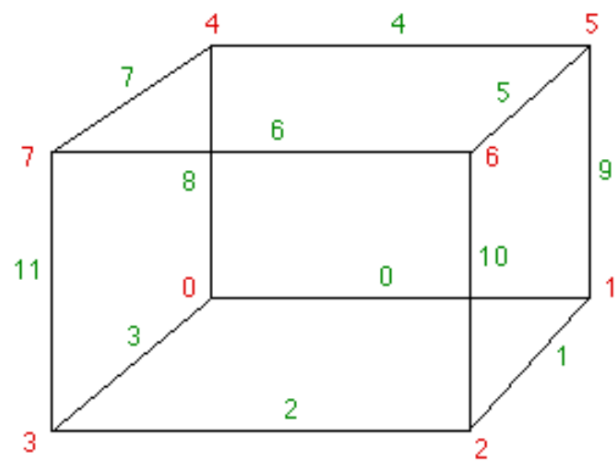
Vertex 3 inside  
(or outside) the  
volume

Isosurface facet

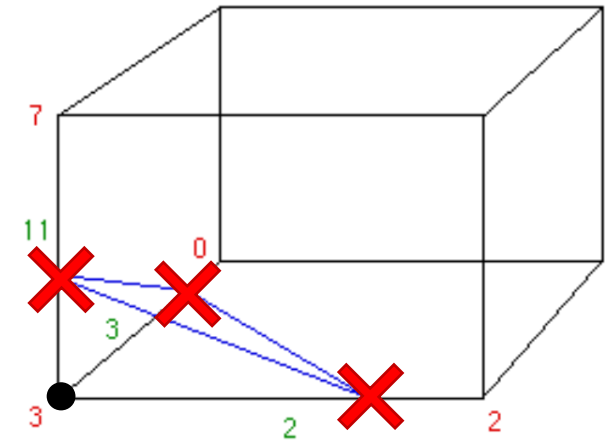
# “The” Implementation: Step 1 Find Intersecting Edges

by Paul Bourke

Ref: “Polygonising a scalar field”, <http://paulbourke.net/geometry/polygonise/>

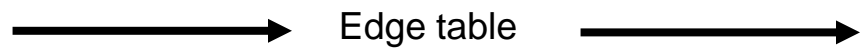


Edge index  
Vertex index



Vertex 3 inside  
(or outside) the  
volume  
  
Isosurface facet

vertex	< iso.
7	0
6	0
5	0
4	0
3	1
2	0
1	0
0	0



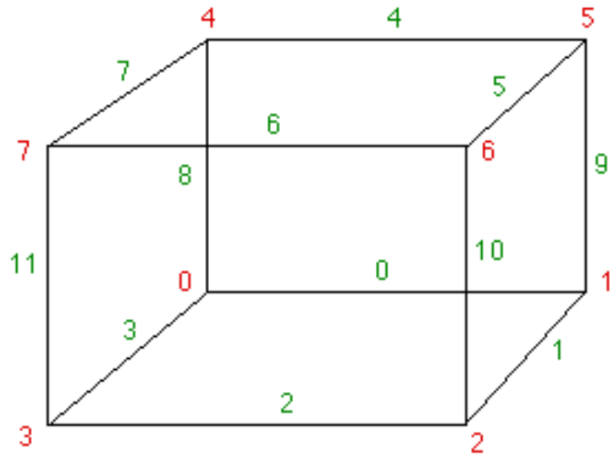
intersect	edge
1	11
0	10
0	9
0	8
0	7
0	6
0	5
0	4
1	3
1	2
0	1
0	0



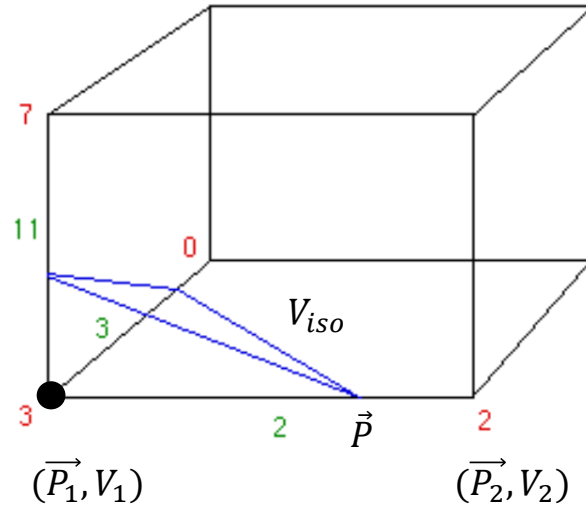
# “The” Implementation: Step 2 Find Intersection Locations

by Paul Bourke

Ref: “Polygonising a scalar field”, <http://paulbourke.net/geometry/polygonise/>



Edge index  
Vertex index



Vertex 3 inside  
(or outside) the  
volume

Isosurface facet

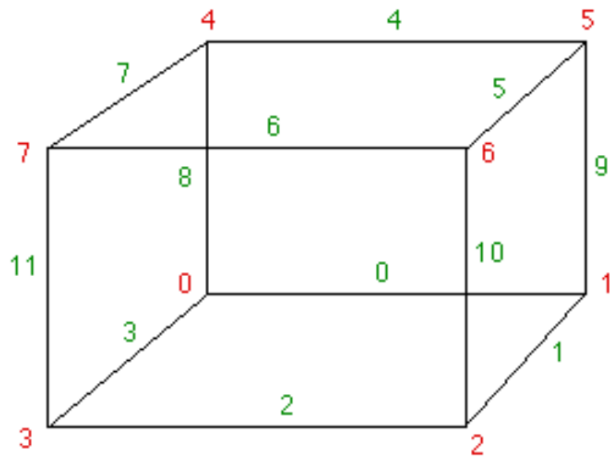
Linear Interpolation:

$$\vec{P} = \vec{P}_1 + \frac{V_{iso} - V_1}{V_2 - V_1} \vec{P}_2$$

# “The” Implementation: Step 3 List Triangles

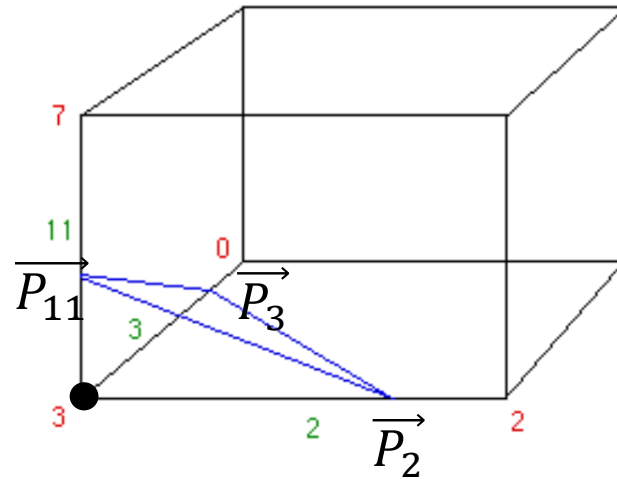
by Paul Bourke

Ref: “Polygonising a scalar field”, <http://paulbourke.net/geometry/polygonise/>



Triangle list = [ (3,11,2) ]

Edge index  
Vertex index



Vertex 3 inside  
(or outside) the  
volume

Isosurface facet

$\vec{P_3}$  = [ intersect at edge 3 ]

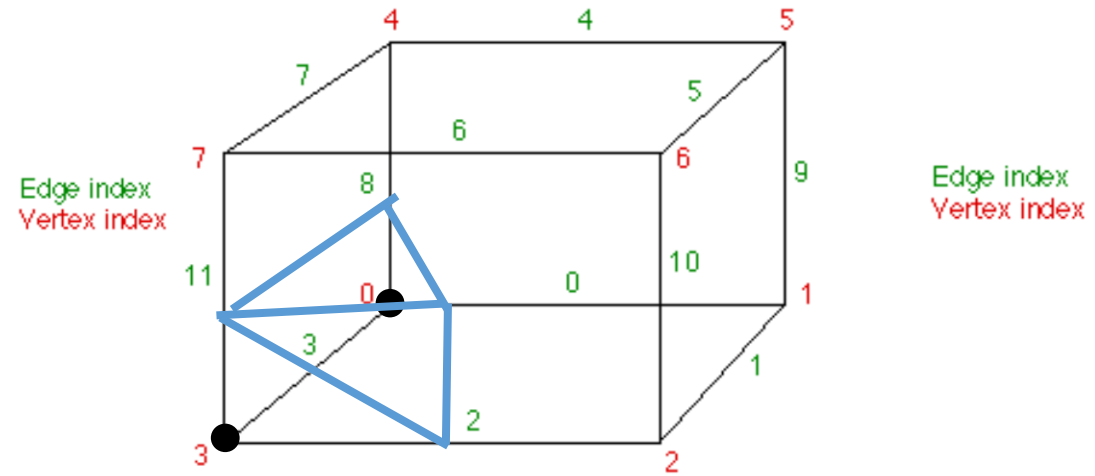
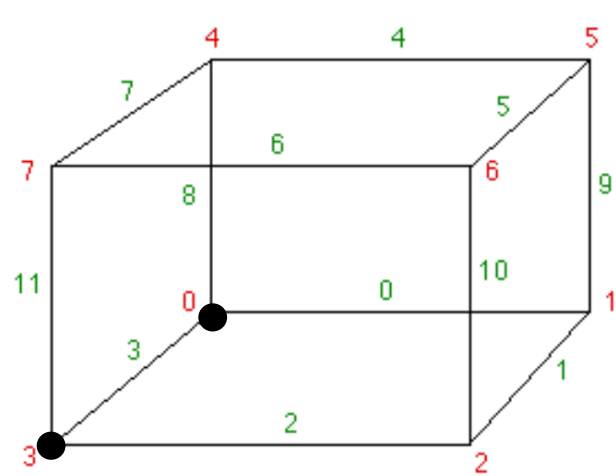
$\vec{P_{11}}$  = [ intersect at edge 11 ]

$\vec{P_2}$  = [ intersect at edge 2 ]

# Exercise

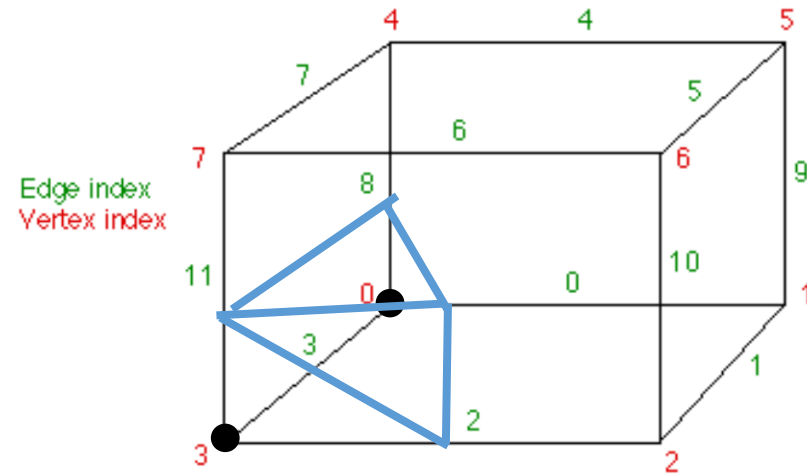
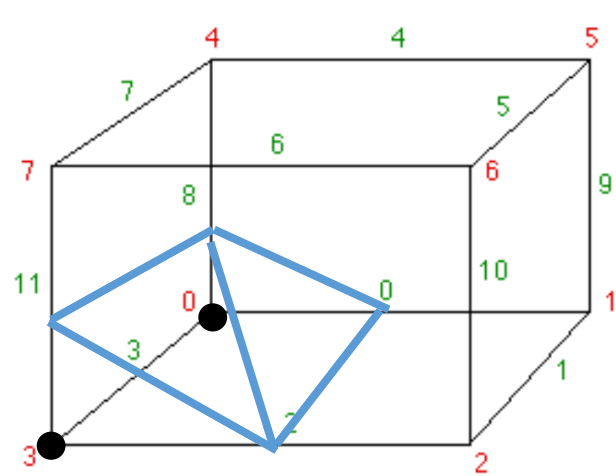
by Paul Bourke

Ref: "Polygonising a scalar field", <http://paulbourke.net/geometry/polygonise/>



vertex	< iso.	Edge table		intersect	edge
7	0	→	→	1	11
6	0			0	10
5	0			0	9
4	0			1	8
3	1			0	7
2	0			0	6
1	0			0	5
0	1			0	4
				0	3
				1	2
				0	1
				1	0

# Possible Ambiguity?



Edge index  
Vertex index

Edge index  
Vertex index

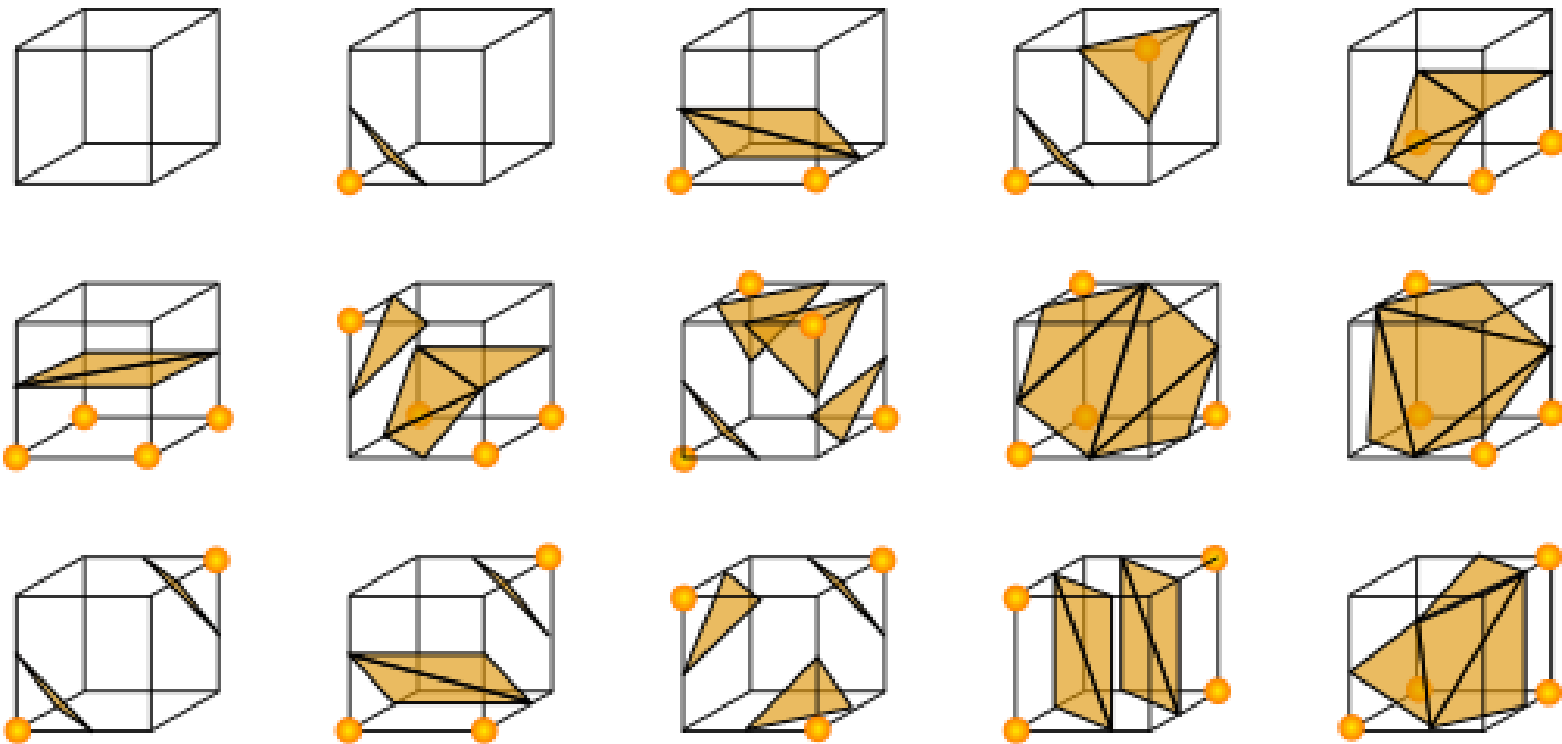
# Constructing the Edge Table

1. Realize that there are  $2^8 = 256$  cases to consider.

2. Use symmetries to reduce to 15 unique cases

3. Go through each case and resolve ambiguity

vertex	< iso.		intersect	edge
7	0	<div> <div></div> <div>Edge table</div> <div></div> </div>	1	11
6	0		0	10
5	0		0	9
4	0		0	8
3	1		0	7
2	0		0	6
1	0		0	5
0	0		0	4
			1	3
			1	2
			0	1
			0	0

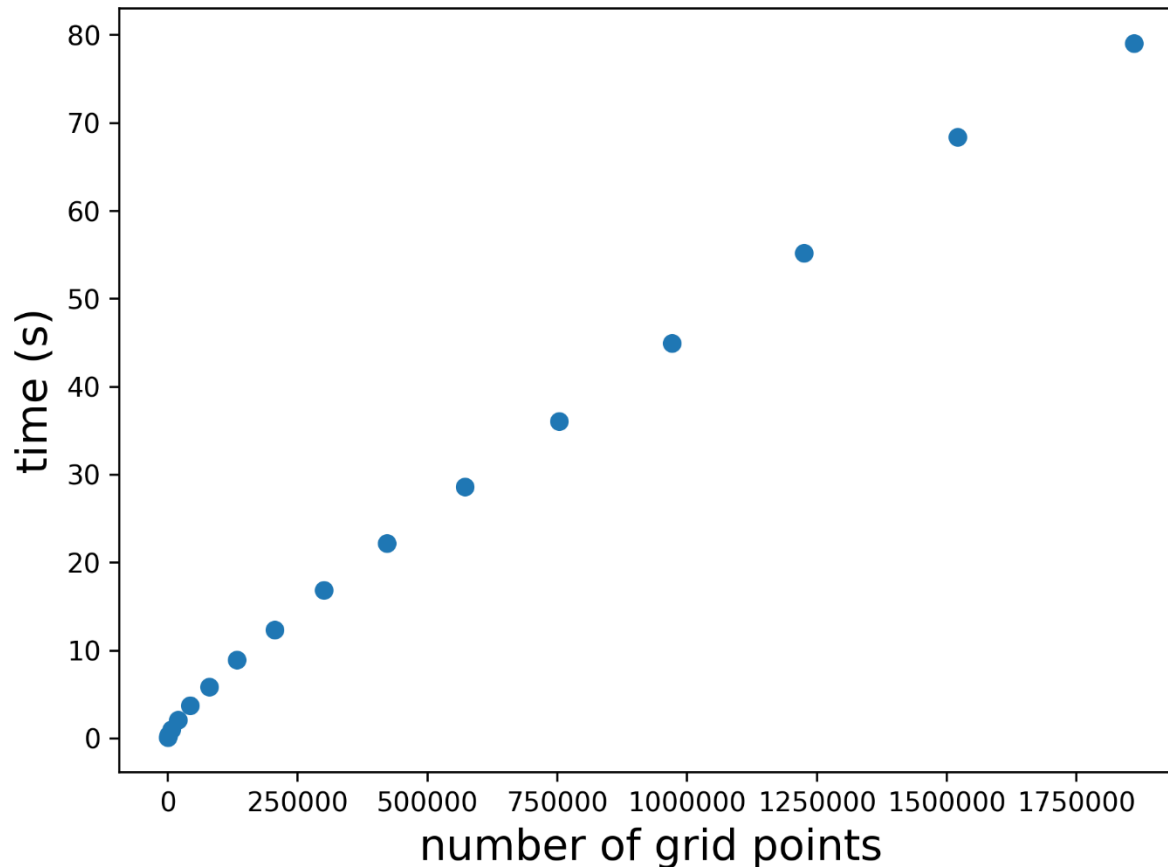


# Timing

The marching cubes algorithm is almost entirely table look-up

Slowness in matplotlib is likely due to 2D projection overhead (matplotlib does not do actual 3D rendering)

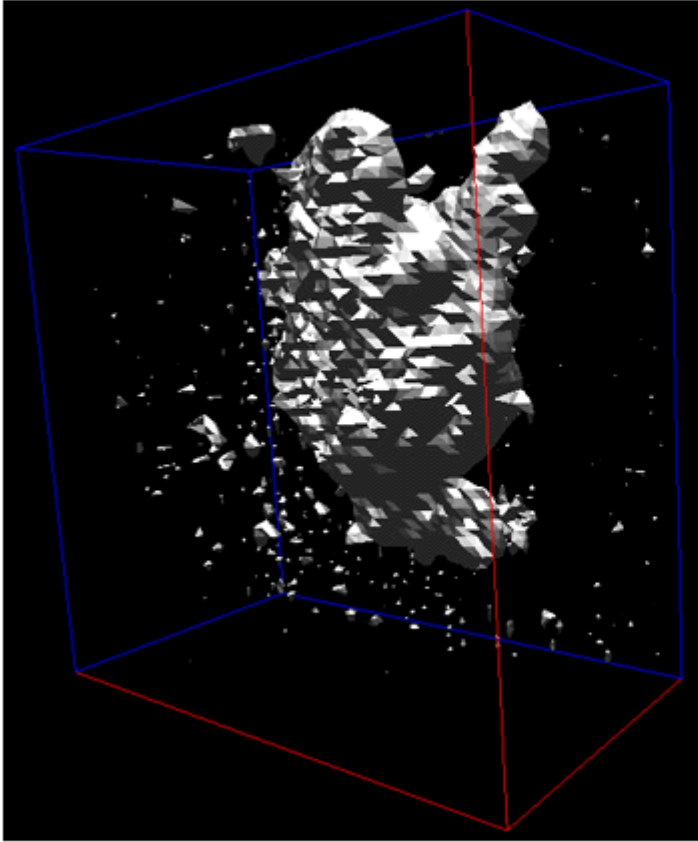
Timing of `skimage.measure.marching_cubes_lewiner`  
on 1 core of i7-4702MQ @ 2.2GHz



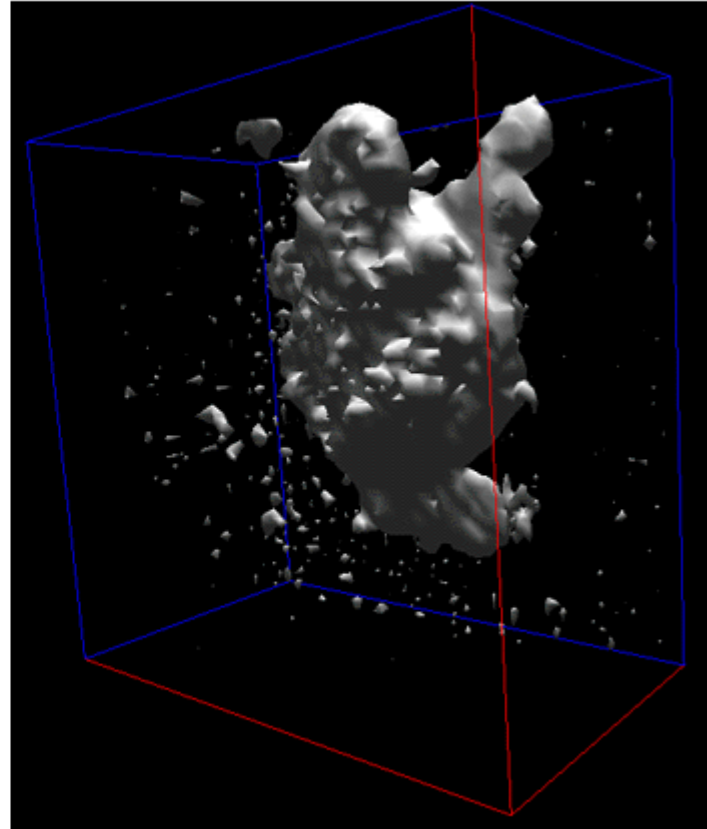
# Normal Mapping

Dot **averaged** face normal vectors with light rays to determine luminescence

No vertex normals (OpenGL)



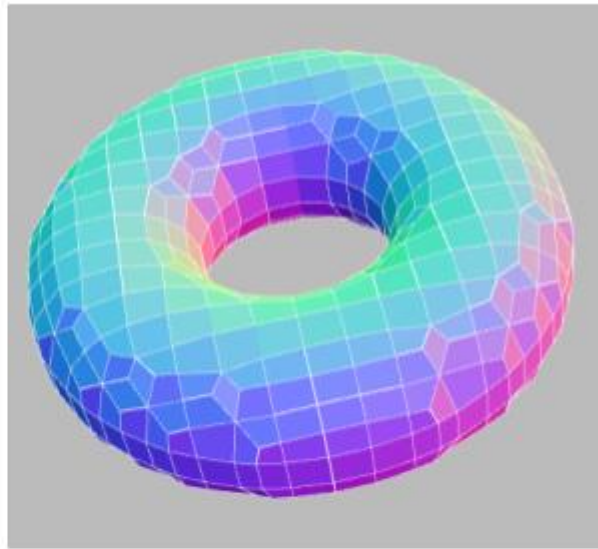
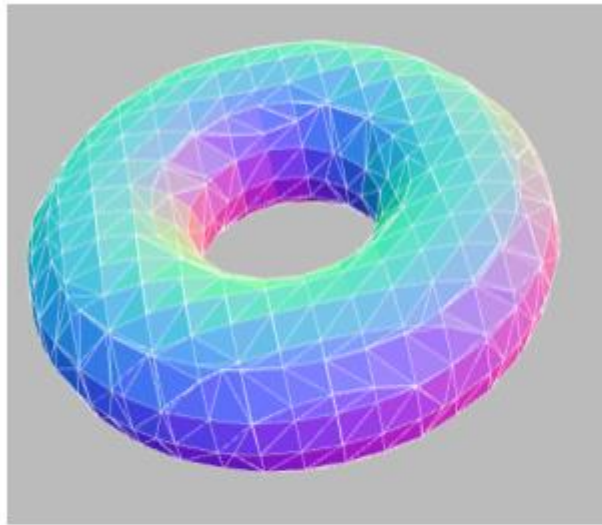
Vertex Normals (OpenGL)



## Modern Replacement: Surface Nets

Compute the edge crossings (like we did in marching cubes) and then take their center of mass as the vertex for each cube.

Fewer vertices than marching cubes



Left: Marching cubes. Right: Naive surface nets.



## References:

- [1] Paul Bourke, “[Polygonising a scalar field](#)” (1994)
- [2] Mikola Lysenko, “[Smooth Voxel Terrain](#)” (2012)
- [3] Sarah F. Gibson, “[Constrained Elastic Surface Nets](#)” (1999)

## Utilities:

a [click bate](#) you will NOT regret falling for!

plot [basis](#) from PySCF

plot [orbitals](#) from PySCF (call the show\_moR function)

plot [spin density](#) from PySCF